

Figure 1: MyChron 3 XG LOG

## Introduction

**MyChron 3 XG LOG** represents the perfect synthesis between MyChron 3 Gold XG and MyChron 3 LOG advanced for car applications: this new logger merges the functionalities and the features of those 2 previous loggers and constitutes a milestone moment in AIM data logger history.

**MyChron 3 XG LOG** monitors and displays RPM, 5 fully configurable analog inputs (pressure, temperature, potentiometers, Lambda probe and Pitot tube, speed sensors), 2 speed inputs, internal lateral G-sensor (to map tracks), gear number and lap (split) times.

**MyChron 3 XG LOG** is interfaceable with the most common ECU, like Bosch, Carmo, Efi, MecTronic, MoTec and others, through an **RS232 cable** or a **CAN cable** (connected to the gauge ECU-RPM-POWER input) to sample the data out coming from the ECU.

To have a complete list of compatibles ECUs, communication protocol and connection with AIM logger, please refer to "<u>documents</u>" page of our website <u>www.aim-sportline.com</u>, where You find a dedicated datasheet called ECU-AIM logger.

The logger records the following parameters:

- 5 analog inputs: pressure and temperature sensors (VDO, thermoresistors, thermocouples), potentiometers (linear and circular), Lambda probe and Pitot tube;
- lap and split times;
- 2 speed inputs;
- Internal lateral G-sensor to map tracks;
- Gear number;
- Logger's temperature;
- All the channels acquired from the engine's ECU.

Data are stored in a huge 8 Mbytes internal flash memory and may be downloaded to a PC through an USB cable.

For further information on the gauge's display, please refer to the following drawing.



Figure 2: MyChron 3 XG LOG display

# Installation notes

- We recommend to choose a place where the instrument will not be in contact with oil or fuel, be sure that the gauge is not installed too close to heat sources and protect the instrument from vibrations;
- We remind you that MyChron 3 XG LOG is not equipped with internal batteries, so it needs to be powered by an external 9 – 15V power source (i.e. the car's battery). Do not exceed these limits.



In order to correctly measure the lateral g-force using the internal accelerometer, it is suggested to install the gauge with the Junction box's front panel perpendicular to the vehicle's speed, as shown in Figure 3.

Figure 3: How to correctly install Your MyChron 3 XG LOG (Junction box's top side view)

- Once the gauge and the Junction box have been correctly installed, you may plug all the sensors inside the junction box front panel;
- Moreover, you may connect the gauge to the engine's ECU using the serial/CAN cable.



## How to use the ECU-RPM-POWER input

Your **MyChron 3 XG LOG** is equipped with a 7 pins female connector labelled as ECU-RPM-POWER. This multi-purpose connector is used for:

- ECU connection CAN protocol
- ECU connection RS232 serial protocol
- Power input: external 9 15V power source, RED (+) and BLACK
  (-) wires;
- RPM input: the logger has 2 supplementary RPM inputs for coil (150-400 V) or square wave (8-50 V) RPM signals. Usually the RPM signal is sampled from the ECU and so you do not need to use one of these 2 wires.

To connect your **MyChron 3 XG LOG** to the ECU, please use the serial RS232 / CAN cable and connect it to the gauge as shown in Figure 4.

Please note that your ECU may be equipped with a CAN or with an RS232 serial communication protocol, so you do not have to connect both "CAN + / CAN -" and "RS232 TX / RS232 RX" wires to the ECU, but only the ones concerning the correct communication protocol.



Figure 4: How to connect Your MyChron 3 XG LOG To the ECU

## How to connect MyChron 3 XG LOG to the PC

In order to connect your **MyChron 3 XG LOG** to the PC, please use the USB data download cable and plug it both in the gauge's USB port and in the PC's USB port, as explained in Figure 5. Moreover, **please use a 9-15 Volts external power source** to switch on the gauge.



Figure 6: How to connect Your MyChron 3 XG LOG to the Pc



### Software

Once the logger installed and the sensors plugged in, to configure the logger, please use **Race Studio 2**, the software developed by Aim to configure its instruments and analyze stored data.

Please run **Race Studio 2**, select "**M3 LOG / VISOR/XGLOG**", press "System manager" button and follow these steps:



### 1) Set the input channels

Press "Channels" button to set the sensors installed on your car; this window appears.

🔲 System manager - M3LOG 📃 🗖 🔀										
General Display Channels			Show ADC of	ounts	Customize sens	10:				
	Logger identifi	gger identification Transmit			Receive		Online		Calibrate	
N Channel ident	Enabled/disal	Channel n	ame	Sampling	Sensor type	Measuri	Lower bound	Upper bound	Param. 1	~
1 SPD_1	Enabled	Speed_1		10 Hz	Speed	km/h	0.000	250.000	1666.	I.
2 CH_1	Enabled	Channel_1	1	10 Hz	Thermore spin	*C	0.000	150.000		- 1
3 CH_2	Enabled	Channel_3	2	10 H	Thermocouple	*C	0.000	150.000		
4 CH_3	Enabled	Channel_3	3	10 H	Thermocouple	] *C	0.000	150.000		
5 CH_4	Enabled	Channel_	4	10 H	AIRBOX pressure sensor - XC	°C	0.000	1000.000		
6 CH_5 I	Enabled	Channel_!	5	10 H	Oil press. ( RENAULT )	°C	0.000	50.000		
7 ACC_1	Enabled	Acc_1		10 H	Air press. (RENAULT)	g 0.x	-3.000	3.000		
8 LOG_TMP	Enabled	Datalogge	r_Temp	10 H	Zero based potentiometer	°C	0.000	50.000		
9 BATT	Enabled	Battery		1 H	Mid zero potentiometer	V 0.x	5.000	15.000		
10 ECU_1	Enabled	PECTEL_	RPM	10 Hz	Lambda sond	rpm	0.000	20000.000		
11 ECU_2	Enabled	PECTEL_	WHEELSPD	10 Hz	Lanbua sonu waxin Ly TITN	km/h	0.000	350.000		
12 ECU_3	Enabled	PECTEL_	OILPRESS	5 Hz	Pressure sensor	bar 0.>	0.000	5.000		
13 ECU_4	Enabled	PECTEL_	OILTEMP	2 Hz	Temperature sensor	°C	0.000	150.000		
14 ECU_5	Enabled	PECTEL_	WATERTEMP	2 Hz	Temperature sensor	°C	0.000	150.000		
Configuration name		L	ogger name		Vehicle name	Availa	ible time	Total	frequency	
pippo M3L0		0G - Advanced		pluto	1.48.3	32 (h.m.s)	16	i1 (Hz)		

To set an input channel, double-click on the cell corresponding to the desired one: the pop up window circled above appears.

#### 2) How to configure the gauge

Once set the desired input channels, press "Configuration" button to set all the other parameters. The window below appears.



G-force sensor and "potentiometer distance" sensor need to be auto-calibrated pressing

To correctly configure your **MyChron 3 XG LOG**, please set all parameters reported in the configuration window shown in the previous figure:

- Display language.
- Obscuring time and Number of splits.
- Speed channel, wheel circumference and pulses per wheel revolution.
- Channels and alarms concerning the 2 display pages.
- Gear channel: calculated or none

### 3) Transmit the configuration

Once the input channels set and configured to transmit the configuration to the logger please press "OK" button and than "Transmit" button on the following wndow. Please note: to transmit the configuration, the gauge must be switched on and connected to the PC, as shown in Figure 5.

#### 4) Calibrate/auto-calibrate sensors

After configuration transmission you have to calibrate/auto-calibrate the sensors.

"Potentiometer distance" and "Internal lateral accelerometer" sensors need autocalibration, while "Mid zero potentiometer", "zero based potentiometer" and "on-board gear sensor" need calibration. Please press "Calibrate" button and this window appears



## **5) Re-transmit the configuration** Once the calibration/autocalibration has



button "Click here to auto-calibrate all sensors in the list".

To calibrate "on-board" gear sensor, "Mid zero potentiometer" or "zero based potentiometer", click on the corresponding "Calibrate" button and follow the instructions prompted on your PC's monitor.

Please note: calibration/auto calibration procedure is fundamental to acquire correct data.

finished, it is absolutely necessary to retransmit the configuration to your **MyChron 3 XG LOG** pressing the "Transmit" button.



## **Dimensions in millimetres [inches]**



## **Channels 1÷5 pinout**

Pin	Function	Pin	Function
1	Analog input	3	+V battery
2	GND	4	V reference

## Speed channel pinout

Pi	n Function	Pir	n Function
1	Speed 1	3	+V battery
2	GND	4	Speed 2

# Beacon channel pinout

Pi	n Function	Pir	n Function
1	Magn. / Opt. codified lap	3	+V battery
2	GND	4	Optic not codified lap

# **ECU-RPM-POWER** channel pinout

Pin	Function	Piı	n Function
1 2	CAN + CAN -	5 6	RS232 RX RPM 150-400 V (coil
3 4	+ V batt. RS232 TX	7	input) and Sq. Wave (>8V) GND



4 & 7 pins female Binder 712 connectors pinout: external view

# **Technical characteristics**

General characteristics	Value
Input channels	5
Input ch. from ECU	Max. 64
Max sampling freq. per channel	Up to 200 Hz
Total sampling	1000 Hz
trequency	
Internal g-sensor	Biaxial, ±10g
External power	From 9 to 15 VDC
Voltage output (V	4.5 V (for
ref.)	potentiometers)
Internal memory	8 Mb flash EPROM
ECU interface	Serial / CAN protocol
PC interface	300 kbyte/sec USB
	port
Other characteristic	s Value
M3 XG LOG dimensio	ons 126x92x24 mm
Display dimensions	87X48 mm
Environmental	IP 65